

Sensors for Mobility

Friday, May 31, 2019

8:00 am **Introduction & Objectives** Waguih Ishak, SPRC

Session I

8:10 Designing the next generation of LiDAR sensors for autonomous mobility Jason Eichenholz, Luminar

8:40 Automotive LiDARs Ming Wu, UC Berkeley

9:10 On chip LIDAR based on all-passive nonlinear isolator Kiyoul Yang, Stanford

9:40 Sensors for Automotive Dragos Maciuca, Ford

10:10 am Break

Session II

10:30 Inverse designed optical phased arrays for LIDAR Dries Vercruyssen, Stanford

11:00 Micromechanical phased arrays for Microsecond random access scanning Olav Solgaard, Stanford

11:30 Deep Optics Gordon Wetzstein, Stanford

12:00pm Lunch & Poster Session

Session III

1:00 Fabrication of components for optical & electrical sensors Robert Visser, Applied Materials

1:30 Towards all-optical detection of chiral biomarkers with dielectric metasurfaces Jennifer Dionne, Stanford

2:00 Real-Time Biosensors for continuously measuring H. Tom Soh, Stanford

2:30 Smaller, smarter, cheaper optical sensors; the golden age of diffractive optics? Xavier Lafosse, Corning

3:00pm Break

Session IV

3:30 3D Sensing for Mobile phones Charles Roxlo, Finisar

4:00 13xx to 15xx Laser and Detector Arrays on GaAs for Next Generation Sensing Sabeur Siala, SJC

4:30 Nanoporous glass for sensing applications Navaneetha Subbaiyan, Corning

5:00 pm Concluding Remarks & Reception

6:00 pm Adjourn